

Representation Theory:

A Friendly Introduction

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Preliminaries

What is representation theory?

- Representation theory is a branch of mathematics that studies abstract algebraic structures by representing their elements as linear transformations of vector spaces
- When such abstract algebraic object is being represented on a finite-dimensional vector space, its elements are described by matrices and its algebraic operations are described by matrix addition and/or matrix multiplication
- Representation theory reduces abstract algebra problems to linear algebra problems

Where is representation theory applied?

- Algebra and number theory
- Category theory
- Quantum physics: the theory of elementary particles and more
- Fourier analysis
- And much more!

Definition

A **group** (G, \star) is a set G equipped with some binary operation $\star: G \times G \rightarrow G, (a, b) \mapsto a \star b$ that satisfies 3 conditions:

- Associativity: $(a \star b) \star c = a \star (b \star c) \quad \forall a, b, c \in G$
- Unitarity: $\exists e \in G$ such that $e \star a = a = a \star e \quad \forall a \in G$ (often we denote $e = 1 = 1_G$)
- Invertibility: $\forall a \in G \exists b \in G$ such that $a \star b = e$ and $b \star a = e$ (often we denote $b = a^{-1}$)

Examples

- $(\mathbb{Z}, +)$, $(\mathbb{k}, +)$, $(\mathbb{k}^* = \mathbb{k} \setminus \{0\}, \cdot)$, where $\mathbb{k} = \mathbb{Q}, \mathbb{R}, \mathbb{C}$
- $(\mathbb{Z}/n\mathbb{Z} = \{\bar{0}, \bar{1}, \dots, \overline{n-1}\}, +)$
- $(GL_n(\mathbb{k}) = \{A \in M_n(\mathbb{k}) \mid A \text{ is invertible}\}, \cdot)$
- $(SO_3(\mathbb{R}) = \{A \in GL_3(\mathbb{R}) \mid AA^T = I_3 \text{ det } A = 1\}, \cdot)$
- For any set X , $(S_X = \{\varphi: X \rightarrow X \mid \varphi \text{ is bijective}\}, \circ)$; when $X = \{1, 2, \dots, n\}$, we write $S_X = S_n$
- For any \mathbb{k} -vector space V ,
 $(GL_{\mathbb{k}}(V) = \{\varphi: V \rightarrow V \mid \varphi \text{ is } \mathbb{k}\text{-linear and invertible}\}, \circ)$

Definition

If (G, \star) and (H, \spadesuit) are groups, then a *group morphism* $\rho: (G, \star) \rightarrow (H, \spadesuit)$ is a map $\rho: G \rightarrow H$ such that $\rho(a \star b) = \rho(a) \spadesuit \rho(b) \forall a, b \in G$.

From the group axioms, one can deduce that $\rho(1_G) = 1_H$ and $\rho(a^{-1}) = \rho(a)^{-1} \forall a \in G$.

Examples

- $\iota: (\mathbb{R}, +) \rightarrow (\mathbb{C}, +), a \mapsto a$
- $\pi: (\mathbb{Z}, +) \rightarrow (\mathbb{Z}/n\mathbb{Z}, +), a \mapsto \bar{a}$
- $\varphi: (G, \star) \rightarrow (S_G, \circ), g \mapsto \varphi_g, \text{ where } \varphi_g: a \mapsto g \star a$

Definition

Let (G, \star) be a group and X be a set. A *group action of (G, \star) on X* is a group morphism $\alpha: (G, \star) \rightarrow (S_X, \circ)$.

So what does this mean:

- $\alpha(1_G) = \text{id}_X$, so $\alpha(1_G)(x) = \text{id}_X(x) = x$ for $x \in X$
- $\alpha(g \star h) = \alpha(g) \circ \alpha(h)$, so $\alpha(g \star h)(x) = \alpha(g)(\alpha(h)(x))$ for $g, h \in G$ and $x \in X$

If we instead use $g \bullet x = \alpha(g)(x)$, then the above conditions may be more familiar:

- $1_G \bullet x = x$ for $x \in X$
- $(g \star h) \bullet x = g \bullet (h \bullet x)$ for $g, h \in G$ and $x \in X$

Example

The group (D_3, \cdot) , where

$D_3 = \{1, a, a^2, b, ab, a^2b \mid a^3 = b^2 = (ab)^2 = 1\}$, acts on the Triangle by means of symmetry.

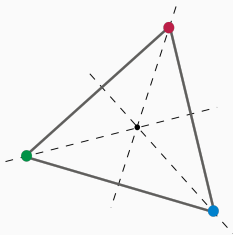


Figure 1: Symmetries of the Triangle

Example

The group $(SO_3(\mathbb{R}), \cdot)$ acts on the vector space \mathbb{R}^3 via matrix multiplication:

$$Ax \in \mathbb{R}^3 \quad \text{for} \quad A \in SO_3(\mathbb{R}), x \in \mathbb{R}^3$$

The group $(SO_3(\mathbb{R}), \cdot)$ is known as ‘the 3D rotation group’ because it is the group of all rotations about the origin of \mathbb{R}^3 .

Moreover, this group action is \mathbb{R} -linear, so this is our first example of a ‘group representation’.

Representation Theory of Groups

Definition

Let (G, \star) be a group and V be a \mathbb{k} -vector space. A **representation of (G, \star) on V** is a group morphism $\rho: (G, \star) \rightarrow (\mathrm{GL}_{\mathbb{k}}(V), \circ)$. We say that the representation is **finite-dimensional** when $\dim_{\mathbb{k}} V < \infty$.

So really, group representations are a special case of group actions.

If $V \cong \mathbb{k}^n$, then $\mathrm{GL}_{\mathbb{k}}(V) \cong \mathrm{GL}_{\mathbb{k}}(\mathbb{k}^n) \cong \mathrm{GL}_n(\mathbb{k})$.

Examples

- $\text{triv}: (G, \star) \rightarrow (\text{GL}_{\mathbb{C}}(\mathbb{C}), \circ) \cong (\mathbb{C}^*, \cdot)$, where $\text{triv}(g) = 1 \forall g \in G$
- $\chi: (\mathbb{Z}/n\mathbb{Z}, +) \rightarrow (\text{GL}_{\mathbb{C}}(\mathbb{C}), \circ) \cong (\mathbb{C}^*, \cdot)$, where $\chi(\overline{m}) = e^{2\pi im/n}$
- $\varphi: (S_3, \circ) \rightarrow (\text{GL}_{\mathbb{C}}(\mathbb{C}^2), \circ) \cong (\text{GL}_2(\mathbb{C}), \cdot)$, where

$$\varphi((1\ 2)) = \begin{bmatrix} -1 & -1 \\ 0 & 1 \end{bmatrix}, \quad \varphi((1\ 2\ 3)) = \begin{bmatrix} -1 & -1 \\ 1 & 0 \end{bmatrix}$$

Definition

Given two representations $\rho_1: (G, \star) \rightarrow (\mathrm{GL}_{\mathbb{k}}(V_1), \circ)$ and $\rho_2: (G, \star) \rightarrow (\mathrm{GL}_{\mathbb{k}}(V_2), \circ)$, a **morphism from ρ_1 to ρ_2** is a \mathbb{k} -linear map $T: V_1 \rightarrow V_2$ such that the following diagram commutes $\forall g \in G$:

$$\begin{array}{ccc} V_1 & \xrightarrow{\rho_1(g)} & V_1 \\ T \downarrow & & \downarrow T \\ V_2 & \xrightarrow{\rho_2(g)} & V_2 \end{array}$$

If T is invertible, we say that T is an **isomorphism from ρ_1 to ρ_2** and write $\rho_1 \cong \rho_2$.

Proposition-Definition

Given two representations $\rho_1: (G, \star) \rightarrow (\mathrm{GL}_{\mathbb{k}}(V_1), \circ)$ and $\rho_2: (G, \star) \rightarrow (\mathrm{GL}_{\mathbb{k}}(V_2), \circ)$, the map $\rho_1 \oplus \rho_2: G \rightarrow \mathrm{GL}_{\mathbb{k}}(V_1 \oplus V_2)$, given by $(\rho_1 \oplus \rho_2)(g)((v_1, v_2)) = (\rho_1(g)(v_1), \rho_2(g)(v_2))$, determines a representation of (G, \star) on $V_1 \oplus V_2$ called the **direct sum representation of ρ_1 and ρ_2** .

Given representations $\rho_1: (G, \star) \rightarrow (\mathrm{GL}_m(\mathbb{k}), \cdot)$ and $\rho_2: (G, \star) \rightarrow (\mathrm{GL}_n(\mathbb{k}), \cdot)$, their direct sum is the representation $\rho_1 \oplus \rho_2: (G, \star) \rightarrow (\mathrm{GL}_{m+n}(\mathbb{k}), \cdot)$, where

$$(\rho_1 \oplus \rho_2)(g) = \begin{bmatrix} \rho_1(g) & 0 \\ 0 & \rho_2(g) \end{bmatrix}$$

Example (Permutation Representation)

$\psi: (S_n, \circ) \rightarrow (\mathrm{GL}_{\mathbb{C}}(\mathbb{C}^n), \circ), \sigma \mapsto \psi_{\sigma}$, where $\psi_{\sigma}(e_i) = e_{\sigma(i)}$ and e_1, \dots, e_n are the standard basis vectors of \mathbb{C}^n

The subspaces $V_1 = \mathbb{C}(e_1 + \dots + e_n) = \{\sum_i \lambda_i e_i \mid \lambda_1 = \dots = \lambda_n\}$ and $V_2 = \{\sum_i \lambda_i e_i \mid \sum_i \lambda_i = 0\}$ are invariant under $\psi_{\sigma} \forall \sigma \in S_n$. Moreover, $\mathbb{C}^n = V_1 \oplus V_2$

Therefore, $\psi|_{V_1}: (S_n, \circ) \rightarrow (\mathrm{GL}_{\mathbb{C}}(V_1), \circ), \sigma \mapsto \psi_{\sigma}$ and $\psi|_{V_2}: (S_n, \circ) \rightarrow (\mathrm{GL}_{\mathbb{C}}(V_2), \circ), \sigma \mapsto \psi_{\sigma}$ are group representations as well

In particular, $\psi \cong \psi|_{V_1} \oplus \psi|_{V_2}$

Definition

Given a representation $\rho: (G, \star) \rightarrow (\mathrm{GL}_{\mathbb{k}}(V), \circ)$ and a subspace W of V , we say W is (G, \star) -invariant if $\rho(g)W \subseteq W \forall g \in G$.

In this case, there is an induced representation

$\rho|_W: (G, \star) \rightarrow (\mathrm{GL}_{\mathbb{k}}(W), \circ)$ given by $\rho|_W(g) = \rho(g)|_W$.

Definition

A (non-zero) representation $\rho: (G, \star) \rightarrow (\mathrm{GL}_{\mathbb{k}}(V), \circ)$ is **irreducible** if the only (G, \star) -invariant subspaces of V are $\{0\}$ and V .

Example (Permutation Representation)

$\psi: (S_n, \circ) \rightarrow (\mathrm{GL}_{\mathbb{C}}(\mathbb{C}^n), \circ)$, $\sigma \mapsto \psi_{\sigma}$, where $\psi_{\sigma}(e_i) = e_{\sigma(i)}$ and e_1, \dots, e_n are the standard basis vectors of \mathbb{C}^n

The subspaces $V_1 = \mathbb{C}(e_1 + \dots + e_n) = \{\sum_i \lambda_i e_i \mid \lambda_1 = \dots = \lambda_n\}$ and $V_2 = \{\sum_i \lambda_i e_i \mid \sum_i \lambda_i = 0\}$ are (S_n, \circ) -invariant

Moreover, the representations $\psi|_{V_1}: (S_n, \circ) \rightarrow (\mathrm{GL}_{\mathbb{C}}(V_1), \circ)$ and $\psi|_{V_2}: (S_n, \circ) \rightarrow (\mathrm{GL}_{\mathbb{C}}(V_2), \circ)$ are irreducible

So we have a decomposition into irreducibles: $\psi \cong \psi|_{V_1} \oplus \psi|_{V_2}$

Definition

A representation $\rho: (G, \star) \rightarrow (\mathrm{GL}_{\mathbb{k}}(V), \circ)$ is **semisimple** if there exists a decomposition $V = V_1 \oplus \cdots \oplus V_n$, where each V_i is (G, \star) -invariant and each $\rho|_{V_i}$ is irreducible ($\forall i = 1, \dots, n$)

Theorem (Maschke)

Every (finite-dimensional) representation of a finite group is semisimple (assuming $\mathrm{char} \mathbb{k} \nmid |G|$).

So: classifying all possible irreducible (fin-dim) representations of a finite group (G, \star) (up to isomorphism) will classify all possible (fin-dim) representations (up to isomorphism)

Example

Setting $\omega_n = e^{2\pi i/n}$, then $\chi_k: (\mathbb{Z}/n\mathbb{Z}, +) \rightarrow (\mathbb{C}^*, \cdot), \bar{m} \mapsto \omega_n^{km}$ is a representation for each $k = 1, \dots, n-1$. The representations $\chi_0, \dots, \chi_{n-1}$ classify the distinct irreducible representations of $(\mathbb{Z}/n\mathbb{Z}, +)$ up to isomorphism.

Theorem

Let $\{\rho_i : (G, \star) \rightarrow (\mathrm{GL}_{\mathbb{k}}(V_i), \circ)\}_{i=1, \dots, n}$ be all the distinct irreducible representations of a finite group (G, \star) up to isomorphism and let $d_i = \dim_{\mathbb{k}} V_i$. Then

$$|G| = d_1^2 + \cdots + d_n^2.$$

Moreover, $d_i \mid |G|$ for each $i = 1, \dots, n$.

Theorem

The number of all distinct irreducible representations of a finite group (G, \star) (up to isomorphism) is equal to the number of conjugacy classes of (G, \star) .

Definition

The **tensor product** of two \mathbb{k} -vector spaces V and W is the new \mathbb{k} -vector space $V \otimes W = \text{span}_{\mathbb{k}}\{v \otimes w \mid v \in V, w \in W\}$, where $(-)\otimes(-)$ is \mathbb{k} -bilinear:

$$\begin{aligned}(\lambda_1 v_1 + \lambda_2 v_2) \otimes w &= \lambda_1(v_1 \otimes w) + \lambda_2(v_2 \otimes w), \\ v \otimes (\lambda_1 w_1 + \lambda_2 w_2) &= \lambda_1(v \otimes w_1) + \lambda_2(v \otimes w_2),\end{aligned}$$

where $v, v_1, v_2 \in V, w, w_1, w_2 \in W, \lambda_1, \lambda_2 \in \mathbb{k}$.

If V has basis $\{a_1, \dots, a_m\}$ and W has basis $\{b_1, \dots, b_n\}$, then $V \otimes W$ has basis $\{a_i \otimes b_j \mid i = 1, \dots, m, j = 1, \dots, n\}$.

Proposition-Definition

Given two representations $\rho_1: (G, \star) \rightarrow (\mathrm{GL}_{\mathbb{k}}(V_1), \circ)$ and $\rho_2: (G, \star) \rightarrow (\mathrm{GL}_{\mathbb{k}}(V_2), \circ)$, the map $\rho_1 \otimes \rho_2: G \rightarrow \mathrm{GL}_{\mathbb{k}}(V_1 \otimes V_2)$, given by $(\rho_1 \otimes \rho_2)(g)((v_1 \otimes v_2)) = \rho_1(g)(v_1) \otimes \rho_2(g)(v_2)$, determines a representation of (G, \star) on $V_1 \otimes V_2$ called the **tensor product representation of ρ_1 and ρ_2** .

A famous theorem in group theory proven using representation theory (no alternative proof was found until the 1970's):

Burnside's Theorem

Let (G, \star) be a group of order $p^a q^b$, where p and q are prime. Then (G, \star) is solvable.

The dream:

- Classify all irreducible representations
- There has been success with more well-understood algebraic objects when restricting to finite-dimensional representations
- What about for infinite dimensional representations? Not really

Representation Theory of Associative Algebras

So, what next?

Definition

A (unital, associative) \mathbb{k} -algebra $A = (A, +, \cdot)$ is a \mathbb{k} -vector space $(A, +)$ such that:

- $\exists e \in A$ such that $e \cdot a = a = a \cdot e \forall a \in A$ (usually, we denote $e = 1_A = 1$)
- $\lambda(a \cdot b) = (\lambda a) \cdot b = a \cdot (\lambda b) \forall a, b \in A, \forall \lambda \in \mathbb{k}$
- $(a \cdot b) \cdot c = a \cdot (b \cdot c) \forall a, b, c \in A$
- $a \cdot (b + c) = (a \cdot b) + (a \cdot c) \forall a, b, c \in A$
- $(b + c) \cdot a = (b \cdot a) + (c \cdot a) \forall a, b, c \in A$

Examples

- $(\mathbb{k}, +, \cdot)$ is a \mathbb{k} -algebra
- The polynomial ring $(\mathbb{k}[x_1, \dots, x_n], +, \cdot)$ is a \mathbb{k} -algebra
- For a group (G, \star) , the group algebra $(\mathbb{k}[G], +, \star)$ is a \mathbb{k} -algebra
- For a complex Lie algebra \mathfrak{g} , the universal enveloping algebra $(\mathfrak{U}(\mathfrak{g}), +, \cdot)$ is a \mathbb{C} -algebra
- For a \mathbb{k} -vector space, $(\text{End}_{\mathbb{k}}(V) = \{\varphi: V \rightarrow V \mid \varphi \text{ is } \mathbb{k}\text{-linear}\}, +, \circ)$ is a \mathbb{k} -algebra
- $(M_n(\mathbb{k}), +, \circ)$ is a \mathbb{k} -algebra

Definition

If $(A, +, \cdot)$ and $(B, +, \cdot)$ are \mathbb{k} -algebras, then an **algebra morphism** $\rho: (A, +, \cdot) \rightarrow (B, +, \cdot)$ is a \mathbb{k} -linear map $\rho: A \rightarrow B$ such that

- $\rho(1_A) = 1_B$
- $\rho(a_1 a_2) = \rho(a_1) \rho(a_2) \quad \forall a_1, a_2 \in A$

Definition

Let $(A, +, \cdot)$ be a \mathbb{k} -algebra and V be a \mathbb{k} -vector space. A **representation of $(A, +, \cdot)$ on V** is an algebra morphism $\rho: (A, +, \cdot) \rightarrow (\text{End}_{\mathbb{k}}(V), +, \circ)$.

An algebra rep $\varphi: (A, +, \cdot) \rightarrow (\text{End}_{\mathbb{k}}(V), +, \circ) = V$ is a (left) A -module

A group rep $\rho: (G, \star) \rightarrow (\text{GL}_{\mathbb{k}}(V), \circ) = V$ is a (left) $\mathbb{k}[G]$ -module

A Lie algebra rep $\psi: (\mathfrak{g}, +, [\cdot, \cdot]) \rightarrow (\mathfrak{gl}_{\mathbb{k}}(V), +, [\cdot, \cdot]) = V$ is a (left) $\mathfrak{U}(\mathfrak{g})$ -module

So representation theory is a study of module theory

Similar machinery from group representations are available for algebra representations, such as direct products

However a tensor product of algebra representations

$\rho_1: (A, +, \cdot) \rightarrow (\text{End}_{\mathbb{k}}(V_1), +, \circ)$, $\rho_2: (A, +, \cdot) \rightarrow (\text{End}_{\mathbb{k}}(V_2), +, \circ)$ will not be a representation of A , but rather of $A \otimes A$

Algebras for which the tensor product of its representations is again a representation of itself are called **Hopf algebras**

Quantum groups are important examples of Hopf algebras

End